

EEE4114F: Digital Signal Processing

Class Test

7 March 2019

Name:

Student number:

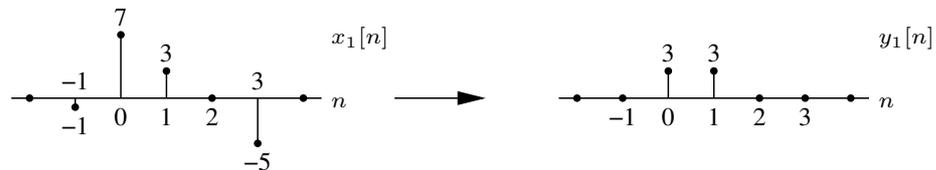
Information

- The test is closed-book.
 - This test has *four* questions, totalling 20 marks.
 - Answer *all* the questions.
 - You have 60 minutes.
 - An information sheet is attached.
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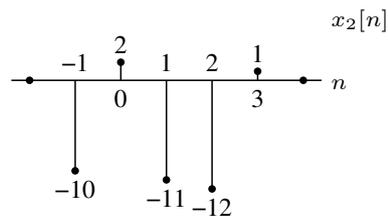
1. (5 marks) The output $y[n]$ of a median filter is given by

$$y[n] = \text{med}(x[n-1], x[n], x[n+1]).$$

Here the median function, $\text{med}(\)$, lists the 3 samples in descending order and selects the value in the middle of the list. For example, the input $x_1[n]$ generates the output $y_1[n]$ below:



- (a) Is the system causal? Why?
 (b) Is the system stable? Why?
 (c) Comment on whether the above median filter is linear. Justify your comments and construct a simple relevant example to illustrate your conclusion. For this purpose you may want to use the example pair given above and the input sequence below:



2. (5 marks) Let $x[n]$ and $v[n]$ be defined as follows:

$$x[n] = \delta[n - 1] - \delta[n + 1] \quad \text{and} \quad v[n] = a\delta[n] + b\delta[n - 1] + c\delta[n - 2].$$

Suppose now that $y[n] = v[n] * x[n]$ gives

$$y[n] = -\delta[n + 1] - 2\delta[n] + 2\delta[n - 2] + \delta[n - 3].$$

- (a) Sketch the signals involved.
- (b) Specify values for a , b , and c .

3. (5 marks) Consider the discrete LTI system represented by

$$y[n] = x[n] - x[n - 1]$$

where $x[n]$ and $y[n]$ are the input and output respectively.

- (a) Determine and plot the impulse response $h[n]$. Is the system stable?
- (b) Determine and plot the step response corresponding to $x[n] = u[n]$.
- (c) Find $H(e^{j\omega})$ and plot its magnitude.
- (d) Determine and plot the response to the input $x[n] = (-1)^n$.

4. (5 marks) A LTI system has a step response of

$$g[n] = n \left(\frac{1}{2}\right)^n u[n].$$

In other words, when the input is $x[n] = u[n]$ then the output is $y[n] = g[n]$ above.

- (a) Is the system causal? Why?
- (b) Find the Fourier transform of $g[n]$.
- (c) Find an expression for its impulse response. You may want to use the fact that $u[n] - u[n - 1] = \delta[n]$.

Discrete-time Fourier transform properties

Sequences $x[n], y[n]$	Transforms $X(e^{j\omega}), Y(e^{j\omega})$	Property
$ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$	Linearity
$x[n - n_d]$	$e^{-j\omega n_d} X(e^{j\omega})$	Time shift
$e^{j\omega_0 n} x[n]$	$X(e^{j(\omega - \omega_0)})$	Frequency shift
$x[-n]$	$X(e^{-j\omega})$	Time reversal
$nx[n]$	$j \frac{dX(e^{j\omega})}{d\omega}$	Frequency diff.
$x[n] * y[n]$	$X(e^{j\omega})Y(e^{j\omega})$	Convolution
$x[n]y[n]$	$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta})Y(e^{j(\omega - \theta)})d\theta$	Modulation

Common discrete-time Fourier transform pairs

Sequence	Fourier transform
$\delta[n]$	1
$\delta[n - n_0]$	$e^{-j\omega n_0}$
1 ($-\infty < n < \infty$)	$\sum_{k=-\infty}^{\infty} 2\pi\delta(\omega + 2\pi k)$
$a^n u[n]$ ($ a < 1$)	$\frac{1}{1 - ae^{-j\omega}}$
$u[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi\delta(\omega + 2\pi k)$
$(n + 1)a^n u[n]$ ($ a < 1$)	$\frac{1}{(1 - ae^{-j\omega})^2}$
$\frac{\sin(\omega_c n)}{\pi n}$	$X(e^{j\omega}) = \begin{cases} 1 & \omega < \omega_c \\ 0 & \omega_c < \omega \leq \pi \end{cases}$
$x[n] = \begin{cases} 1 & 0 \leq n \leq M \\ 0 & \text{otherwise} \end{cases}$	$\frac{\sin[\omega(M+1)/2]}{\sin(\omega/2)} e^{-j\omega M/2}$
$e^{j\omega_0 n}$	$\sum_{k=-\infty}^{\infty} 2\pi\delta(\omega - \omega_0 + 2\pi k)$

Z-transform properties

Sequences $x[n], y[n]$	Transforms $X(z), Y(z)$	ROC	Property
$ax[n] + by[n]$	$aX(z) + bY(z)$	ROC contains $R_x \cap R_y$	Linearity
$x[n - n_d]$	$z^{-n_d} X(z)$	ROC = R_x	Time shift
$z_0^n x[n]$	$X(z/z_0)$	ROC = $ z_0 R_x$	Frequency scale
$x^*[-n]$	$X^*(1/z^*)$	ROC = $\frac{1}{R_x}$	Time reversal
$nx[n]$	$-z \frac{dX(z)}{dz}$	ROC = R_x	Frequency diff.
$x[n] * y[n]$	$X(z)Y(z)$	ROC contains $R_x \cap R_y$	Convolution
$x^*[n]$	$X^*(z^*)$	ROC = R_x	Conjugation

Common z-transform pairs

Sequence	Transform	ROC
$\delta[n]$	1	All z
$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
$-u[-n - 1]$	$\frac{1}{1 - z^{-1}}$	$ z < 1$
$\delta[n - m]$	z^{-m}	All z except 0 or ∞
$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z > a $
$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z < a $
$na^n u[n]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
$-na^n u[-n - 1]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z < a $
$\begin{cases} a^n & 0 \leq n \leq N - 1 \\ 0 & \text{otherwise} \end{cases}$	$\frac{1 - a^N z^{-N}}{1 - az^{-1}}$	$ z > 0$
$\cos(\omega_0 n)u[n]$	$\frac{1 - \cos(\omega_0)z^{-1}}{1 - 2\cos(\omega_0)z^{-1} + z^{-2}}$	$ z > 1$
$r^n \cos(\omega_0 n)u[n]$	$\frac{1 - r\cos(\omega_0)z^{-1}}{1 - 2r\cos(\omega_0)z^{-1} + r^2 z^{-2}}$	$ z > r $

