

EEE4001F: Digital Signal Processing

Class Test 2

22 April 2010

SOLUTIONS

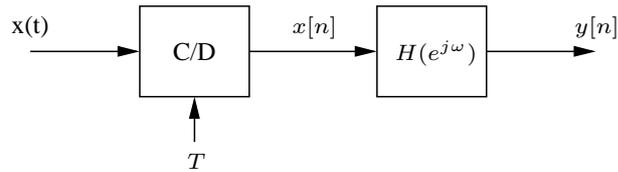
Name:

Student number:

Information

- The test is closed-book.
 - This test has *four* questions, totalling 20 marks.
 - Answer *all* the questions.
 - You have 45 minutes.
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1. (5 marks) Consider the system below



where $T = 0.001$ s and

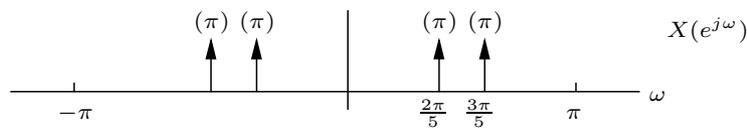
$$H(e^{j\omega}) = \begin{cases} 1 & |\omega| \leq 0.5\pi \\ 0 & \text{otherwise} \end{cases}$$

for $-\pi \leq \omega \leq \pi$. Find the output $y[n]$ if the input is $x(t) = \cos(400\pi t) + \cos(600\pi t)$.

The discretised input is

$$\begin{aligned} x[n] &= x(nT) = \cos\left(\frac{400}{1000}\pi n\right) + \cos\left(\frac{600}{1000}\pi n\right) = \cos\left(\frac{2\pi}{5}n\right) + \cos\left(\frac{3\pi}{5}n\right) \\ &= \frac{1}{2}e^{j\frac{2\pi}{5}n} + \frac{1}{2}e^{-j\frac{2\pi}{5}n} + \frac{1}{2}e^{j\frac{3\pi}{5}n} + \frac{1}{2}e^{-j\frac{3\pi}{5}n}. \end{aligned}$$

In the frequency domain this is



and the filter removes the two impulses at frequencies $\omega = \pm\frac{3\pi}{5}$, and hence the $\cos\left(\frac{3\pi}{5}n\right)$ term. The output is therefore just the remaining term

$$y[n] = \cos\left(\frac{2\pi}{5}n\right).$$

2. (5 marks) Consider the following discrete-time signals $x[n]$ and $y[n]$:

$$x[n] = 0.2 \cos(0.2\pi n) \quad \text{and} \quad y[n] = 0.2 \sin(0.2\pi n).$$

- (a) Show that the 10-point DFT of $x[n]$ is $X[k] = \delta[k - 1] + \delta[k - 9]$ over the range $k = 0, \dots, 9$.
- (b) Assuming that the 10-point DFT of $y[n]$ is $Y[k] = -j(\delta[k - 1] - \delta[k - 9])$, use the DFT to determine a *closed-form* expression for the 10-point circular convolution of $x[n]$ and $y[n]$.

(a) The DFT is as follows:

$$\begin{aligned} X[k] &= \sum_{n=0}^9 0.2 \cos\left(\frac{2\pi}{10}n\right) e^{-j\frac{2\pi}{10}kn} = \frac{0.2}{2} \sum_{n=0}^9 (e^{j\frac{2\pi}{10}n} + e^{-j\frac{2\pi}{10}n}) e^{-j\frac{2\pi}{10}kn} \\ &= \frac{1}{10} \sum_{n=0}^9 \left(e^{-j\frac{2\pi}{10}(k-1)n}\right) + \frac{1}{10} \sum_{n=0}^9 \left(e^{-j\frac{2\pi}{10}(k+1)n}\right) \end{aligned}$$

Over the range $k = 0, \dots, 9$ the first term equals zero except when $k = 1$, in which case it equals 1. The second term is similar: one if $k = 9$ and zero otherwise. Thus

$$X[k] = \delta[k - 1] + \delta[k - 9].$$

- (b) Ten-point circular convolution in time corresponds to multiplication in the 10-point DFT domain. Thus we need to take the 10-point DFTs of the signals, multiply them, and find the 10-point inverse DFT of the result.

If $w[n]$ is the 10-point circular convolution of $x[n]$ with $y[n]$, then for $k = 0, \dots, 9$ we have

$$\begin{aligned} W[k] &= X[k]Y[k] = -j(\delta[k - 1] - \delta[k - 9])(\delta[k - 1] + \delta[k - 9]) \\ &= -j(\delta[k - 1] - \delta[k - 9]). \end{aligned}$$

We observe that in this case $W[k] = Y[k]$, so the convolution result must be $w[n] = 0.2 \sin(0.2\pi n)$.

3. (5 marks) A stable system is characterised by the following LCCDE:

$$y[n + 2] - y[n + 1] + \frac{1}{2}y[n] = x[n + 1].$$

- Draw a pole-zero plot of the system.
- Roughly sketch the magnitude response of the system.
- Assuming the system response represents a band-pass filter at a frequency of $\pi/4$ radians/sample, what is the centre frequency of the passband if an analog signal is sampled at 12kHz before filtering?

(a) Taking the z-transform of the LCCDE gives

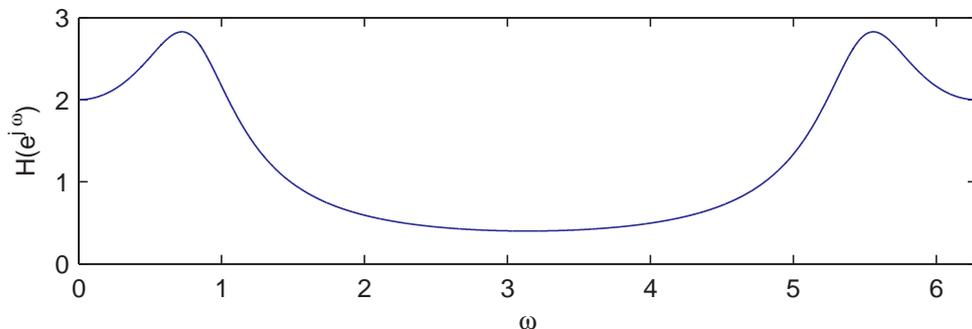
$$z^2Y(z) - zY(z) + \frac{1}{2}Y(z) = zX(z),$$

so

$$H(z) = \frac{Y(z)}{X(z)} = \frac{z}{z^2 - z + \frac{1}{2}}.$$

There is one zero in the numerator at $z = 0$. The roots of the denominator occur at $z = \frac{1}{2} \pm \frac{1}{2}j$. The sketch follows.

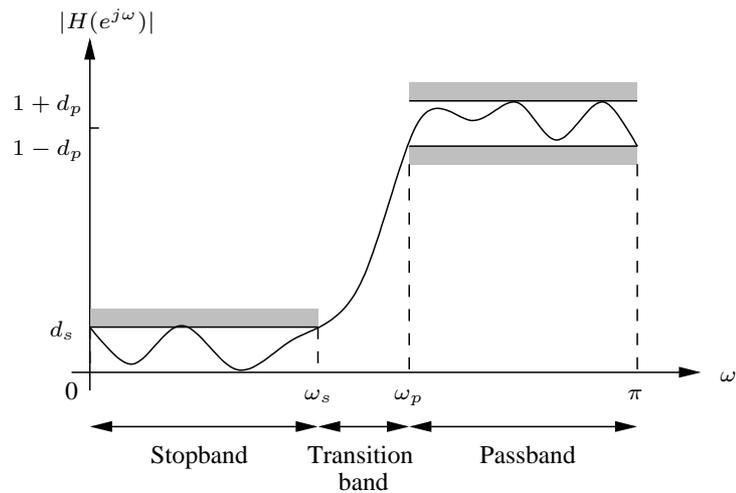
(b) Using graphical methods the magnitude response can be shown to be



(c) For a 12kHz sampling rate the Nyquist frequency is 6kHz and corresponds to $\omega = \pi$. The discrete frequency $\omega = \pi/4$ therefore relates to $6/4 = 1.5$ kHz, and this is the center frequency of the analog system.

4. (5 marks) A particular DSP system is sampled at 48kHz, and requires a highpass filter with a passband ripple of 0.1dB, a transition band of 200Hz, stopband attenuation of 60dB, and a cutoff frequency of 1200Hz. Sketch the appropriate design constraints that the filter must satisfy, specifying parameter values where appropriate. Your frequency axis should be in units of radians per sample.

A prototype highpass filter is as follows:



For a sampling rate of 48kHz the highest frequency that can be represented is 24kHz, and this corresponds to $\omega = \pi$ rad/sample.

The filter must attenuate frequencies of less than 1200Hz by at least 60dB. Thus we must have $\omega_s = \frac{\pi}{24000}1200 = \pi/20$ rad/sample and $d_s = -60$ dB. Similarly, $\omega_p = \frac{\pi}{24000}(1200 + 200)$ rad/sample and $d_p = 0.1$ dB.

Fourier transform properties

Sequences $x[n], y[n]$	Transforms $X(e^{j\omega}), Y(e^{j\omega})$	Property
$ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$	Linearity
$x[n - n_d]$	$e^{-j\omega n_d} X(e^{j\omega})$	Time shift
$e^{j\omega_0 n} x[n]$	$X(e^{j(\omega - \omega_0)})$	Frequency shift
$x[-n]$	$X(e^{-j\omega})$	Time reversal
$nx[n]$	$j \frac{dX(e^{j\omega})}{d\omega}$	Frequency diff.
$x[n] * y[n]$	$X(e^{-j\omega})Y(e^{-j\omega})$	Convolution
$x[n]y[n]$	$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta})Y(e^{j(\omega - \theta)})d\theta$	Modulation

Common Fourier transform pairs

Sequence	Fourier transform
$\delta[n]$	1
$\delta[n - n_0]$	$e^{-j\omega n_0}$
1 $(-\infty < n < \infty)$	$\sum_{k=-\infty}^{\infty} 2\pi\delta(\omega + 2\pi k)$
$a^n u[n]$ $(a < 1)$	$\frac{1}{1 - ae^{-j\omega}}$
$u[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi\delta(\omega + 2\pi k)$
$(n + 1)a^n u[n]$ $(a < 1)$	$\frac{1}{(1 - ae^{-j\omega})^2}$
$\frac{\sin(\omega_c n)}{\pi n}$	$X(e^{j\omega}) = \begin{cases} 1 & \omega < \omega_c \\ 0 & \omega_c < \omega \leq \pi \end{cases}$
$x[n] = \begin{cases} 1 & 0 \leq n \leq M \\ 0 & \text{otherwise} \end{cases}$	$\frac{\sin[\omega(M+1)/2]}{\sin(\omega/2)} e^{-j\omega M/2}$
$e^{j\omega_0 n}$	$\sum_{k=-\infty}^{\infty} 2\pi\delta(\omega - \omega_0 + 2\pi k)$

Common z-transform pairs

Sequence	Transform	ROC
$\delta[n]$	1	All z
$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
$-u[-n - 1]$	$\frac{1}{1 - z^{-1}}$	$ z < 1$
$\delta[n - m]$	z^{-m}	All z except 0 or ∞
$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z > a $
$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z < a $
$na^n u[n]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
$-na^n u[-n - 1]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z < a $
$\begin{cases} a^n & 0 \leq n \leq N - 1, \\ 0 & \text{otherwise} \end{cases}$	$\frac{1 - a^N z^{-N}}{1 - az^{-1}}$	$ z > 0$
$\cos(\omega_0 n)u[n]$	$\frac{1 - \cos(\omega_0)z^{-1}}{1 - 2\cos(\omega_0)z^{-1} + z^{-2}}$	$ z > 1$
$r^n \cos(\omega_0 n)u[n]$	$\frac{1 - r\cos(\omega_0)z^{-1}}{1 - 2r\cos(\omega_0)z^{-1} + r^2 z^{-2}}$	$ z > r$