

EEE401F: Digital Signal Processing

Class Test 1

7 April 2005

SOLUTIONS

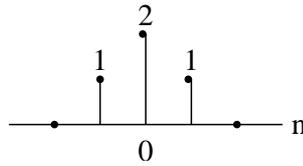
Name:

Student number:

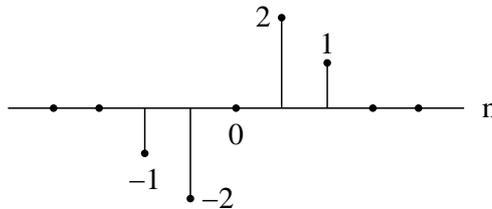
Information

- The test is closed-book.
 - This test has *four* questions, totalling 20 marks.
 - Answer *all* the questions.
 - You have 45 minutes.
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1. (5 marks) A system has an impulse response

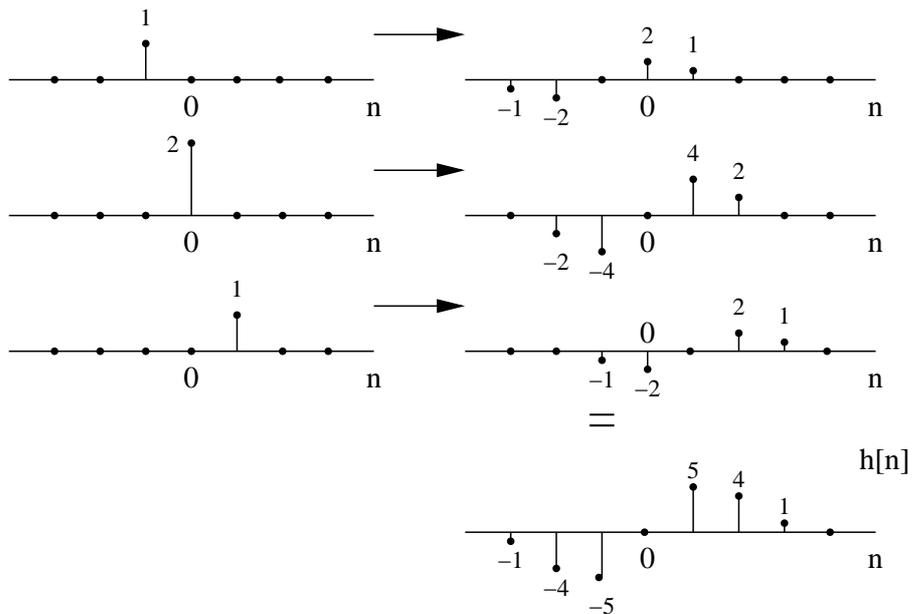


What is the output of the system when the input is the following:



Is the system causal? Is it stable? Why?

The output is the convolution of the two sequences.



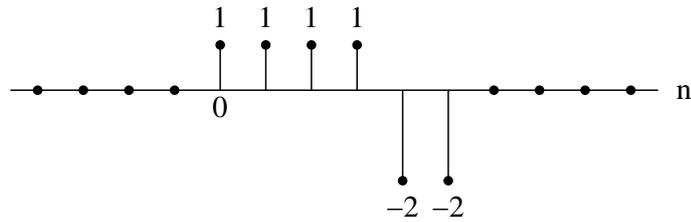
The impulse response is nonzero for some negative values of n , so the system is not causal.

The sum

$$S = \sum_{n=-\infty}^{\infty} |h[n]| = 1 + 2 + 1 = 4 < \infty,$$

so the system is stable.

2. (5 marks) The impulse response of an LTI system is shown below:

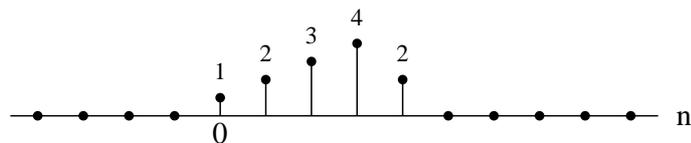


Determine and sketch the response of this system to the input $x[n] = u[n - 4]$.

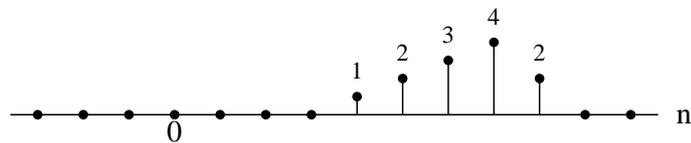
The response of the system to the unit step is

$$g[n] = \sum_{k=-\infty}^{\infty} h[k]u[n - k] = \sum_{k=-\infty}^n h[k],$$

since $u[n - k]$ equals unity for $k \leq n$ and is otherwise zero. Thus the step response is just the accumulated impulse response:



The response to $x(t) = u(t - 4)$ is just the response to the unit step, shifted by 4 units to the right:



3. (5 marks) A highpass FIR filter is characterised by the following impulse response:

$$h[n] = \begin{cases} -0.03 & n = 0 \\ -0.43 & n = 1 \\ 0.56 & n = 2 \\ -0.43 & n = 3 \\ -0.03 & n = 4 \\ 0 & \text{otherwise} \end{cases}$$

Write down the coefficients of an equivalent lowpass filter using frequency translation.

Frequency translation can be represented by the following transform pair:

$$e^{j\omega_0 n} x[n] \xleftrightarrow{\mathcal{F}} X(e^{j(\omega-\omega_0)}),$$

so multiplication by a complex exponential corresponds to shift in frequency.

If the coefficients describe a highpass filter, then the filter must be passing frequencies at $\omega = \pm\pi, \pm3\pi, \dots$, and blocking frequencies $\omega = 0, \pm2\pi, \dots$. If we shift this response by $\omega_0 = \pi$, then we will get a lowpass filter passing $\omega = 0, \pm2\pi, \dots$ and blocking $\omega = \pm\pi, \pm3\pi, \dots$

The impulse response of the corresponding lowpass filter will be

$$h_{\text{LPF}}[n] = e^{j\pi n} h_{\text{HPF}}[n],$$

so

$$h_{\text{LPF}}[n] = \begin{cases} -0.03 & n = 0 \\ 0.43 & n = 1 \\ 0.56 & n = 2 \\ 0.43 & n = 3 \\ -0.03 & n = 4 \\ 0 & \text{otherwise} \end{cases}$$

4. (5 marks) An LTI system has the following system function:

$$H(z) = \frac{z^{-32}}{(1 - \frac{1}{2}z^{-1})(1 - 2z^{-1})}$$

- (a) Sketch the corresponding pole-zero diagram.
- (b) List every possible region of convergence (ROC) for $H(z)$.
- (c) For each ROC, comment on system causality and stability.
- (d) One of the ROCs should correspond to a causal system. In that case only, find the impulse response of the system.