

# EEE2047S EXAM SIGNALS AND SYSTEMS I

University of Cape Town  
Department of Electrical Engineering

November 2021  
2 hours

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## Information

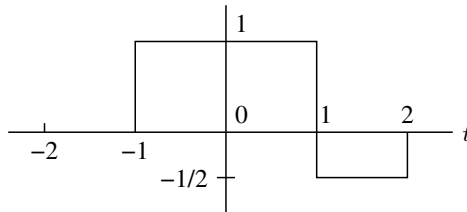
- The exam is closed-book.
  - There are two parts to this exam. Each part must be answered and submitted in separate exam books.
  - **Part A** has *four* questions totalling 40 marks. You must answer all of them.
  - **Part B** has *three* questions totalling 30 marks. You must answer all of them.
  - Marks are awarded based on method and clarity of presentation. Just writing down the answer is not a good strategy.
  - The last page of this exam paper contains an information sheet with standard Fourier and Laplace transforms, transform properties, and some trigonometric identities.
  - You have 2 hours.
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## PART A

The two parts of the exam must be answered in separate sets of exam books.

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1. Let  $g(t)$  be the function



Sketch the following:

(a)  $y_1(t) = g(t - 2)$

(b)  $y_2(t) = g(2 - t)$

(c)  $y_3(t) = g(2t - 2)$

(d)  $y_4(t) = \int_{-\infty}^t g(\tau) d\tau$

(e) The generalised derivative  $y_5(t) = \frac{d}{dt}g(t)$ .

(10 marks)

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2. (a) Find the complex exponential Fourier series of the function

$$x(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT).$$

(b) The signal

$$g(t) = (1 + j)e^{j\omega_0 t} + (1 - j)e^{-j\omega_0 t}$$

can be written in the form

$$g(t) = a \cos(\omega_0 t + b)$$

for some values of  $a$  and  $b$ . Find these values.

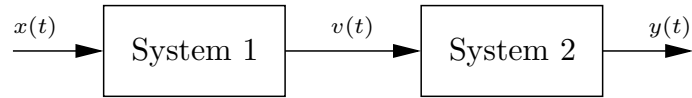
(c) Find the Fourier transform of the signal

$$y(t) = \delta\left(\frac{t - b}{a}\right).$$

(10 marks)

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3. Consider the system below:



Suppose the two components are characterised by the following input-output relationships:

$$\text{System 1: } v(t) = h_1(t) * x(t) \quad \text{with} \quad h_1(t) = u(t)$$

$$\text{System 2: } y(t) = \int_{t-3}^t v(\tau) d\tau.$$

It is easy to show that System 2 is linear, and you may assume this to be true without proving it.

- Show that System 2 is time invariant.
- Is the overall system linear and time invariant? Why?
- Show that the impulse response of System 2 is  $h(t) = u(t) - u(t - 3)$ .
- Determine and plot the impulse response of the overall system.

(10 marks)

4. The following is a valid Fourier transform pair:

$$e^{-|t|} \xleftrightarrow{\mathcal{F}} \frac{2}{\omega^2 + 1}.$$

- Sketch the signal  $x_a(t) = 4e^{-|t|/16}$ .
- Find the Fourier transform of  $x_a(t)$ , and sketch the corresponding magnitude and phase.
- Find the Fourier transform of  $x_b(t) = \frac{1}{(t-1)^2+1}$ .

(10 marks)

## PART B

The two parts of the exam must be answered in separate sets of exam books.

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5. A system is defined by the following differential equation:

$$\frac{d^2y(t)}{dt^2} + \frac{dy(t)}{dt} - 12y(t) = \frac{dx(t)}{dt} - 3x(t).$$

- (a) What is the transfer function  $H(s)$  of this system? Comment on the stability of the system.
- (b) If  $y(0^-) = 1$  and  $\dot{y}(0^-) = 3$ , what is the zero input response of this system? Comment on the properties of this response.

(10 marks)

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6. A system has a transfer function given by

$$H(s) = \frac{1}{s^2 + 6s + 10}.$$

- (a) Show that its impulse response is  $h(t) = e^{-3t} \sin(t)u(t)$ .
- (b) What is the output when the input  $x(t) = e^{-2t}u(t)$ ?

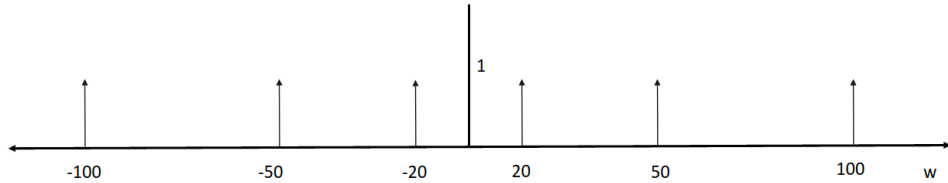
(10 marks)

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7. The frequency response of a filter is defined as follows:

$$H(\omega) = \frac{2500}{2500 + 70j\omega - \omega^2}.$$

- (a) Sketch the magnitude of the frequency response for the range  $-1000 \leq \omega \leq 1000$ .
- (b) What type of filter is this?
- (c) Consider the following signal  $X(\omega)$  being passed through this filter:



Calculate the output  $y(t)$ .

(10 marks)

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# INFORMATION SHEET

## Fourier transform properties

Property	Transform Pair/Property
Linearity	$ax(t) + bv(t) \iff aX(\omega) + bV(\omega)$
Time shift	$x(t - c) \iff X(\omega)e^{-j\omega c}$
Time scaling	$x(at) \iff \frac{1}{ a }X\left(\frac{\omega}{a}\right) \quad a > 0$
Time reversal	$x(-t) \iff X(-\omega) = \overline{X(\omega)}$
Multiplication by power of $t$	$t^n x(t) \iff j^n \frac{d^n}{d\omega^n} X(\omega) \quad n = 1, 2, \dots$
Frequency shift	$x(t)e^{j\omega_0 t} \iff X(\omega - \omega_0) \quad \omega_0 \text{ real}$
Multiplication by $\cos(\omega_0 t)$	$x(t) \cos(\omega_0 t) \iff \frac{1}{2}[X(\omega + \omega_0) + X(\omega - \omega_0)]$
Differentiation in time domain	$\frac{d^n}{dt^n} x(t) \iff (j\omega)^n X(\omega) \quad n = 1, 2, \dots$
Integration	$\int_{-\infty}^t x(\lambda) d\lambda \iff \frac{1}{j\omega} X(\omega) + \pi X(0)\delta(\omega)$
Convolution in time domain	$x(t) * v(t) \iff X(\omega)V(\omega)$
Multiplication in time domain	$x(t)v(t) \iff \frac{1}{2\pi} X(\omega) * V(\omega)$
Parseval's theorem	$\int_{-\infty}^{\infty} x(t)v(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} \overline{X(\omega)}V(\omega) d\omega$
Parseval's theorem (special case)	$\int_{-\infty}^{\infty} x^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X(\omega) ^2 d\omega$
Duality	$X(t) \iff 2\pi x(-\omega)$

## Common Fourier Transform Pairs

$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{j\omega t} d\omega$	$X(\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$
1 $(-\infty < t < \infty)$	$2\pi\delta(\omega)$
$-0.5 + u(t)$	$\frac{1}{j\omega}$
$u(t)$	$\pi\delta(\omega) + \frac{1}{j\omega}$
$\delta(t)$	1
$\delta(t - c)$	$e^{-j\omega c} \quad (c \text{ any real number})$
$e^{-bt}u(t)$	$\frac{1}{j\omega + b} \quad (b > 0)$
$e^{j\omega_0 t}$	$2\pi\delta(\omega - \omega_0) \quad (\omega_0 \text{ any real number})$
$p_\tau(t)$	$\tau \text{sinc} \frac{\tau\omega}{2\pi}$
$\tau \text{sinc} \frac{\tau t}{2\pi}$	$2\pi p_\tau(\omega)$
$\left(1 - \frac{2 t }{\tau}\right) p_\tau(t)$	$\frac{\tau}{2} \text{sinc}^2 \left(\frac{\tau\omega}{4\pi}\right)$
$\frac{\tau}{2} \text{sinc}^2 \frac{\tau t}{4\pi}$	$2\pi \left(1 - \frac{2 \omega }{\tau}\right) p_\tau(\omega)$
$\cos(\omega_0 t + \theta)$	$\pi[e^{-j\theta}\delta(\omega + \omega_0) + e^{j\theta}\delta(\omega - \omega_0)]$
$\sin(\omega_0 t + \theta)$	$j\pi[e^{-j\theta}\delta(\omega + \omega_0) - e^{j\theta}\delta(\omega - \omega_0)]$
$\sum_{n=-\infty}^{\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\frac{2\pi}{T})$

with  $p_\tau(t) = u(t + \tau/2) - u(t - \tau/2)$  and  $\text{sinc}(\lambda) = \sin(\pi\lambda)/(\pi\lambda)$ .

# Laplace transform properties

Property	Transform Pair/Property
Linearity	$ax(t) + bv(t) \iff aX(s) + bV(s)$
Time shift	$x(t-a)u(t-a) \iff e^{-as}X(s) \quad a \geq 0$
Time scaling	$x(at) \iff \frac{1}{a}X\left(\frac{s}{a}\right) \quad a > 0$
Frequency differentiation	$t^n x(t) \iff (-1)^n X^{(n)}(s)$
Frequency shift	$e^{at}x(t) \iff X(s-a)$
Differentiation	$x'(t) \iff sX(s) - x(0^-)$ $x''(t) \iff s^2X(s) - sx(0^-) - x'(0^-)$ $x^{(n)}(t) \iff s^n X(s) - s^{n-1}x(0^-) - \dots - x^{(n-1)}(0^-)$
Integration	$\int_0^t x(\lambda)d\lambda \iff \frac{1}{s}X(s)$ $\int_{-\infty}^t x(\lambda)d\lambda \iff \frac{1}{s}X(s) + \frac{1}{s} \int_{-\infty}^0 x(\lambda)d\lambda$
Time convolution	$x(t) * v(t) \iff X(s)V(s)$
Frequency convolution	$x(t)v(t) \iff \frac{1}{2\pi j} X(s) * V(s)$

Initial value:  $f(0^+) = \lim_{s \rightarrow \infty} sF(s)$

Final value:  $f(\infty) = \lim_{s \rightarrow 0} sF(s)$  with all poles in left-hand plane

## Common Unilateral Laplace Transform Pairs

$x(t) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} X(s)e^{st} ds$	$X(s) = \int_0^\infty x(t)e^{-st} dt$
$\delta(t)$	1
$u(t)$	$\frac{1}{s}$
$tu(t)$	$\frac{1}{s^2}$
$t^n u(t)$	$\frac{n!}{s^{n+1}}$
$e^{\lambda t} u(t)$	$\frac{1}{s-\lambda}$
$te^{\lambda t} u(t)$	$\frac{1}{(s-\lambda)^2}$
$t^n e^{\lambda t} u(t)$	$\frac{n!}{(s-\lambda)^{n+1}}$
$\cos(bt)u(t)$	$\frac{s}{s^2+b^2}$
$\sin(bt)u(t)$	$\frac{b}{s^2+b^2}$
$e^{-at} \cos(bt)u(t)$	$\frac{s+a}{(s+a)^2+b^2}$
$e^{-at} \sin(bt)u(t)$	$\frac{b}{(s+a)^2+b^2}$
$re^{-at} \cos(bt + \theta)u(t)$	$\frac{(r \cos \theta)s + (ar \cos \theta - br \sin \theta)}{s^2 + 2as + (a^2 + b^2)}$
$re^{-at} \cos(bt + \theta)u(t)$	$\frac{0.5re^{j\theta}}{s+a-jb} + \frac{0.5re^{-j\theta}}{s+a+jb}$
$re^{-at} \cos(bt + \theta)u(t)$	$\frac{As+B}{s^2+2as+c}$
	$r = \sqrt{\frac{A^2c+B^2-2ABa}{c-a^2}}, b = \sqrt{c-a^2}, \theta = \tan^{-1} \frac{Aa-b}{A\sqrt{c-a^2}}$

## Trigonometric identities

$$\begin{aligned} \sin(-\theta) &= -\sin(\theta) & \cos(-\theta) &= \cos(\theta) & \tan(-\theta) &= -\tan(\theta) & \sin^2(\theta) + \cos^2(\theta) &= 1 \\ \sin(2\theta) &= 2\sin(\theta)\cos(\theta) & \cos(2\theta) &= \cos^2(\theta) - \sin^2(\theta) = 2\cos^2(\theta) - 1 = 1 - 2\sin^2(\theta) \\ \sin(\theta_1 + \theta_2) &= \sin(\theta_1)\cos(\theta_2) + \cos(\theta_1)\sin(\theta_2) & \cos(\theta_1 + \theta_2) &= \cos(\theta_1)\cos(\theta_2) - \sin(\theta_1)\sin(\theta_2) \\ e^{j\theta} &= \cos(\theta) + j\sin(\theta) \end{aligned}$$