# EEE2047S EXAM SIGNALS AND SYSTEMS I

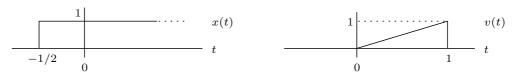
# University of Cape Town Department of Electrical Engineering

# November 2018 2 hours

#### Information

- The exam is closed-book.
- There are 8 questions totaling 75 marks. You must answer all of them.
- Marks are awarded based on method and clarity of presentation. Just writing down the answer is not a good strategy.
- The last two pages of this exam paper contain an information sheet with standard Fourier and Laplace transforms, transform properties, and some trigonometric identities.
- You have 2 hours.

1. Compute the convolution of the following two signals:



(10 marks)

2. Consider the system



with input-output relationship

$$y(t) = \int_{t-1/2}^{t+1/2} x(\tau) d\tau.$$

- (a) Is the system linear? Why?
- (b) Is the system time invariant? Why?
- (c) Is the system causal? Why?
- (d) Show that the impulse response of the system is  $h(t) = p_1(t)$ .
- (e) Find and sketch the output of the system when the input is the unit step x(t) = u(t).

(10 marks)

3. Suppose the signal x(t) can be written as an exponential Fourier series

$$x(t) = e^{-2jt} + je^{-jt} + 2 - je^{jt} + e^{2jt}.$$

- (a) What is the fundamental period of x(t)?
- (b) Plot the magnitude and phase of the Fourier series coefficients of x(t).
- (c) Since x(t) is real it can be written in trigonometric form

$$x(t) = a_0 + \sum_{k=1}^{\infty} a_k \cos(k\omega_0 t + b_k).$$

Specify the value of  $a_0$ , and the values of  $a_k$  and  $b_k$  for all  $k \geq 1$ .

(10 marks)

4. Find the impulse response of the system with frequency response

$$H(\omega) = \frac{j\omega}{j\omega + 4} - \frac{1}{(j\omega + 4)^2}.$$

For the second term it is useful to apply the frequency differentiation property to the pair

$$e^{-bt}u(t) \qquad \stackrel{\mathcal{F}}{\longleftrightarrow} \qquad \frac{1}{j\omega+b} \qquad (b>0).$$

(10 marks)

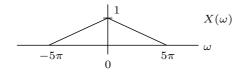
5. A linear system has frequency response

$$H(\omega) = \frac{j\omega}{1 + j\omega}.$$

- (a) What is the DC gain of the system?
- (b) Roughly sketch  $|H(\omega)|$ . What kind of system does this represent?
- (c) Find the impulse response of the system.
- (d) Determine the system response to  $x(t) = \sin(2t)$ .

(10 marks)

6. Suppose x(t) is a signal with the spectrum shown below:



- (a) Find the energy contained in x(t).
- (b) Suppose  $y_1(t) = x(t)\cos(15\pi t)$ . Plot  $Y_1(\omega)$ .
- (c) Suppose  $y_2(t) = p(t)x(t)$  with

$$p(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT)$$

and T = 2/5. Plot  $Y_2(\omega)$ .

(10 marks)

7. A causal system has a Laplace transform

$$F(s) = \frac{s^2 - 4}{s^2 + 6s + 9}.$$

- (a) Specify the locations of the poles and zeros of the system, and draw a pole-zero plot. Is the system stable? Why?
- (b) Find a time-domain expression for the response of the system to a unit step x(t) = u(t).

(10 marks)

8. Consider the initial value problem

$$\frac{d^2}{dt^2}y(t) + 7\frac{d}{dt}y(t) + 12y(t) = 0$$

subject to y(0) = 1 and  $\frac{d}{dt}y(t) = 2$ . Determine Y(s).

(5 marks)

#### INFORMATION SHEET

## Fourier transform properties

Property	Transform Pair/Property
Linearity	$ax(t) + bv(t) \iff aX(\omega) + bV(\omega)$
Time shift	$x(t-c) \iff X(\omega)e^{-j\omega c}$
Time scaling	$x(at) \Longleftrightarrow \frac{1}{a}X(\frac{\omega}{a})  a > 0$
Time reversal	$x(-t) \iff X(-\omega) = \overline{X(\omega)}$
Multiplication by power of $t$	$t^n x(t) \iff j^n \frac{d^n}{d\omega^n} X(\omega)  n = 1, 2, \dots$
Frequency shift	$x(t)e^{j\omega_0 t} \iff X(\omega - \omega_0)  \omega_0 \text{ real}$
Multiplication by $\cos(\omega_0 t)$	$x(t)\cos(\omega_0 t) \iff \frac{1}{2}[X(\omega + \omega_0) + X(\omega - \omega_0)]$
Differentiation in time domain	$\frac{d^n}{dt^n}x(t) \iff (j\omega)^n X(\omega)  n = 1, 2, \dots$
Integration	$\int_{-\infty}^{t} x(\lambda) d\lambda \iff \frac{1}{j\omega} X(\omega) + \pi X(0) \delta(\omega)$
Convolution in time domain	$x(t) * v(t) \iff X(\omega)V(\omega)$
Multiplication in time domain	$x(t)v(t) \iff \frac{1}{2\pi}X(\omega) * V(\omega)$
Parseval's theorem	$\int_{-\infty}^{\infty} x(t)v(t)dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} \overline{X(\omega)}V(\omega)d\omega$
Parseval's theorem (special case)	$\int_{-\infty}^{\infty} x^{2}(t)dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X(\omega) ^{2} d\omega$
Duality	$X(t) \Longleftrightarrow 2\pi x(-\omega)$

#### Common Fourier Transform Pairs

$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$	$X(\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t}dt$
$1  (-\infty < t < \infty)$	$2\pi\delta(\omega)$
-0.5 + u(t)	$\frac{1}{j\omega}$
u(t)	$\pi\delta(\omega) + \frac{1}{j\omega}$
$\delta(t)$	1
$\delta(t-c)$	$e^{-j\omega c}$ (c any real number)
$e^{-bt}u(t)$	$\frac{1}{i\omega+b}$ $(b>0)$
$e^{j\omega_0t}$	$2\pi\delta(\omega-\omega_0)$ ( $\omega_0$ any real number)
$p_{ au}(t)$	$ au \mathrm{sinc} rac{ au \omega}{2\pi}$
$ au \mathrm{sinc} rac{ au t}{2\pi}$	$2\pi p_{ au}(\omega)$
$\left(1-rac{2 t }{ au} ight)p_{ au}(t)$	$\frac{\tau}{2}\mathrm{sinc}^2\left(\frac{\tau\omega}{4\pi}\right)$
$\frac{\tau}{2}$ sinc <sup>2</sup> $\frac{\tau t}{4\pi}$	$2\pi \left(1 - \frac{2 \omega }{\tau}\right) p_{\tau}(\omega)$
$\cos(\omega_0 t + \theta)$	$\pi[e^{-j\theta}\delta(\omega+\omega_0)+e^{j\theta}\delta(\omega-\omega_0)]$
$\sin(\omega_0 t + \theta)$	$j\pi[e^{-j\theta}\delta(\omega+\omega_0)-e^{j\theta}\delta(\omega-\omega_0)]$
$\sum_{n=-\infty}^{\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k \frac{2\pi}{T})$
with $p_{\tau}(t) = u(t + \tau/2) - u(t - \tau)$	$(-2)$ and $\operatorname{sinc}(\lambda) = \sin(\pi \lambda)/(\pi \lambda)$ .

#### Laplace transform properties

Property	Transform Pair/Property
Linearity	$ax(t) + bv(t) \iff aX(s) + bV(s)$
Time shift	$x(t-a)u(t-a) \iff e^{-as}X(s)  a \ge 0$
Time scaling	$x(at) \iff \frac{1}{a}X(\frac{s}{a})  a > 0$
Frequency differentiation	$t^n x(t) \Longleftrightarrow (-1)^n X^{(n)}(s)$
Frequency shift	$e^{at}x(t) \Longleftrightarrow X(s-a)$
Differentiation	$x'(t) \Longleftrightarrow sX(s) - x(0^-)$
	$x''(t) \iff s^2 X(s) - sx(0^-) - x'(0^-)$
	$x^{(n)}(t) \iff s^n X(s) - s^{n-1} x(0^-) - \dots - x^{(n-1)}(0^-)$
Integration	$\int_{0^{-}}^{t} x(\lambda) d\lambda \iff \frac{1}{s} X(s)$
	$\int_{-\infty}^{t} x(\lambda) d\lambda \Longleftrightarrow \frac{1}{s} X(s) + \frac{1}{s} \int_{-\infty}^{0} x(\lambda) d\lambda$
Time convolution	$x(t) * v(t) \Longleftrightarrow X(s)V(s)$
Frequency convolution	$x(t)v(t) \iff \frac{1}{2\pi j}X(s) * V(s)$

Initial value:  $f(0^+) = \lim_{s \to \infty} sF(s)$ 

Final value:  $f(\infty) = \lim_{s\to 0} sF(s)$  with all poles in left-hand plane

#### Common Unilateral Laplace Transform Pairs

$x(t) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} X(s)e^{st} ds$	$X(s) = \int_{0^{-}}^{\infty} x(t)e^{-st} dt$
$\delta(t)$	1
u(t)	$\frac{1}{s}$
tu(t)	$\frac{1}{s^2}$
$t^n u(t)$	$\frac{n!}{s^{n+1}}$
$e^{\lambda t}u(t)$	$\frac{1}{s-\lambda}$
$te^{\lambda t}u(t)$	$\frac{1}{(s-\lambda)^2}$
$t^n e^{\lambda t} u(t)$	$\frac{n!}{(s-\lambda)^{n+1}}$
$\cos(bt)u(t)$	$\frac{s}{s^2+b^2}$
$\sin(bt)u(t)$	$\frac{b}{s^2+b^2}$
$e^{-at}\cos(bt)u(t)$	$\frac{s+a}{(s+a)^2+b^2}$
$e^{-at}\sin(bt)u(t)$	$\frac{b}{(s+a)^2+b^2}$
$re^{-at}\cos(bt+\theta)u(t)$	$\frac{(r\cos\theta)s + (ar\cos\theta - br\sin\theta)}{s^2 + 2as + (a^2 + b^2)}$ $\frac{0.5re^{j\theta}}{s + a - jb} + \frac{0.5re^{-j\theta}}{s + a + jb}$
$re^{-at}\cos(bt+\theta)u(t)$	$rac{0.5re^{j heta}}{s+a-jb}+rac{0.5re^{-j heta}}{s+a+jb}$
$re^{-at}\cos(bt+\theta)u(t)$	$\frac{As+B}{s^2+2as+c}$
	$r = \sqrt{\frac{A^2c + B^2 - 2ABa}{c - a^2}}, \ b = \sqrt{c - a^2}, \ \theta = \tan^{-1} \frac{Aa - b}{A\sqrt{c - a^2}}$

## ${\bf Trigonometric\ identities}$

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\begin{split} & \sin(-\theta) = -\sin(\theta) & \cos(-\theta) = \cos(\theta) & \tan(-\theta) = -\tan(\theta) & \sin^2(\theta) + \cos^2(\theta) = 1 \\ & \sin(2\theta) = 2\sin(\theta)\cos(\theta) & \cos(2\theta) = \cos^2(\theta) - \sin^2(\theta) = 2\cos^2(\theta) - 1 = 1 - 2\sin^2(\theta) \\ & \sin(\theta_1 + \theta_2) = \sin(\theta_1)\cos(\theta_2) + \cos(\theta_1)\sin(\theta_2) & \cos(\theta_1 + \theta_2) = \cos(\theta_1)\cos(\theta_2) - \sin(\theta_1)\sin(\theta_2) \\ & e^{j\theta} = \cos(\theta) + j\sin(\theta) \end{split}
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