

# EEE2035F EXAM SIGNALS AND SYSTEMS I

University of Cape Town  
Department of Electrical Engineering

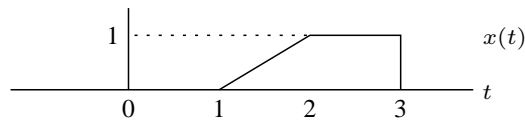
June 2011  
2 hours

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## Information

- The exam is closed-book.
  - There are *eight* questions totalling 80 marks. You must answer all of them.
  - The last page of this exam paper contains an information sheet with standard Fourier transforms, transform properties, and some trigonometric identities.
  - You have 2 hours.
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1. Suppose  $x(t)$  is the signal below:



Sketch the following:

- (a)  $y_1(t) = -2x(t) + 1$
- (b)  $y_2(t) = x(-t + 3)$
- (c)  $y_3(t) = \int_{-\infty}^{\infty} x(\lambda + 1)\delta(t - \lambda)d\lambda$
- (d)  $y_4(t) = \int_0^t x(\lambda)d\lambda$
- (e)  $y_5(t) = \frac{d}{dt}x(t - 1)$
- (f)  $y_6(t) = x(2t - 1)$ .

(15 marks)

2. A linear system has the relationship

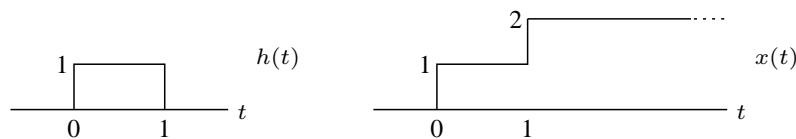
$$y(t) = \int_{-\infty}^{\infty} x(\lambda)g(t - 2\lambda)d\lambda$$

between its input  $x(t)$  and its output  $y(t)$ , where  $g(t) = u(t) - u(t - 4)$ .

- (a) Determine  $y(t)$  when  $x(t) = \delta(t - 1)$ .
- (b) Determine  $y(t)$  when  $x(t) = \delta(t - 2)$ .
- (c) Use your answers for (a) and (b) to determine whether the system is LTI.

(10 marks)

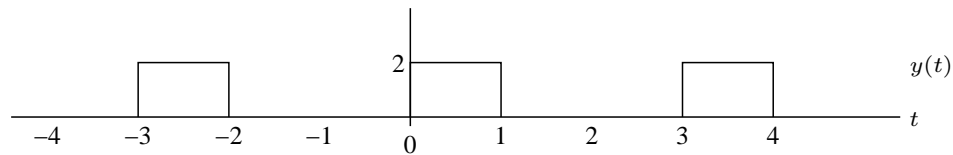
3. A system with impulse response  $h(t)$  is driven by the input signal  $x(t)$ , both of which are shown below:



Find and plot the output signal  $y(t)$ .

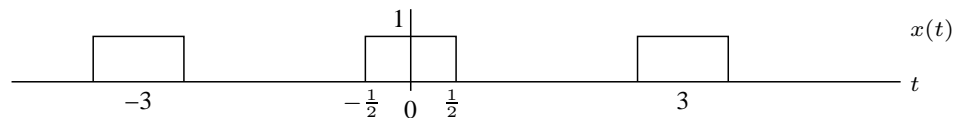
(10 marks)

4. Find the Fourier series representation of the periodic signal  $y(t)$  shown below:



Plot the magnitude and phase of the coefficients over the range  $k = -3, \dots, 3$ .

You may choose to use the fact that the periodic signal



has a Fourier series expansion  $x(t) = \sum_{k=-\infty}^{\infty} d_k e^{jk\frac{2\pi}{3}t}$  with  $d_k = \frac{1}{k\pi} \sin(k\pi/3)$  and  $d_0 = 1/3$ .

(10 marks)

5. A system has the following impulse response:

$$h(t) = 3 \operatorname{sinc}\left(\frac{3t}{2\pi}\right).$$

- Sketch the frequency response  $H(\omega)$  of the system.
- What is the response  $y_1(t)$  to the input signal  $x_1(t) = \cos(t)$ ?
- What is the response  $y_2(t)$  to the input signal  $x_2(t) = \cos(2t)$ ?

(10 marks)

6. If the output of an LTI system is  $y(t) = 3e^{-5t}u(t) - e^{-2t}u(t)$  when the input is  $x(t) = e^{-5t}u(t)$ , what is the impulse response  $h(t)$ ?

(10 marks)

7. (a) Use tables of Fourier transforms and properties to show that the following is a valid Fourier pair:

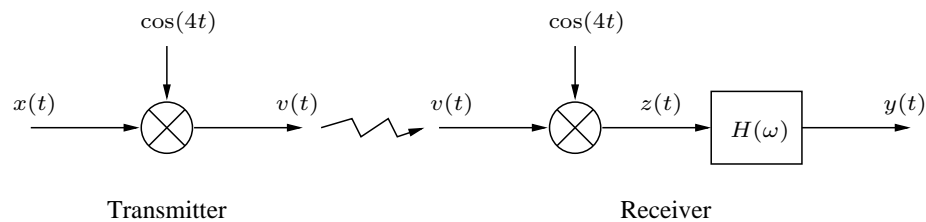
$$e^{-3t}u(t-1) \xleftrightarrow{\mathcal{F}} e^{-3}e^{-j\omega} \frac{1}{3+j\omega}.$$

- (b) Use this result along with other Fourier transform properties to determine the spectrum of the signal

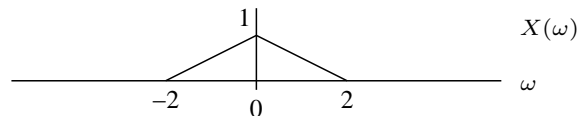
$$x(t) = \frac{d}{dt}(\sin(2t)e^{-3t}u(t-1)).$$

(10 marks)

8. A block diagram of a transmitter and receiver is shown below:



The input signal is assumed to have the following spectrum:



- (a) Sketch the signals  $V(\omega)$  and  $Z(\omega)$ .
- (b) Specify the frequency response  $H(\omega)$  of the filter required for the output  $y(t)$  to be the same as the input  $x(t)$ .

(5 marks)

# INFORMATION SHEET

## Fourier transform properties

Property	Transform Pair/Property
Linearity	$ax(t) + bv(t) \leftrightarrow aX(\omega) + bV(\omega)$
Time shift	$x(t - c) \leftrightarrow X(\omega)e^{-j\omega c}$
Time scaling	$x(at) \leftrightarrow \frac{1}{ a } X\left(\frac{\omega}{a}\right) \quad a > 0$
Time reversal	$x(-t) \leftrightarrow X(-\omega) = \overline{X(\omega)}$
Multiplication by power of $t$	$t^n x(t) \leftrightarrow j^n \frac{d^n}{d\omega^n} X(\omega) \quad n = 1, 2, \dots$
Frequency shift	$x(t)e^{j\omega_0 t} \leftrightarrow X(\omega - \omega_0) \quad \omega_0 \text{ real}$
Multiplication by $\cos(\omega_0 t)$	$x(t) \cos(\omega_0 t) \leftrightarrow \frac{1}{2} [X(\omega + \omega_0) + X(\omega - \omega_0)]$
Differentiation in time domain	$\frac{d^n}{dt^n} x(t) \leftrightarrow (j\omega)^n X(\omega) \quad n = 1, 2, \dots$
Integration	$\int_{-\infty}^t x(\lambda) d\lambda \leftrightarrow \frac{1}{j\omega} X(\omega) + \pi X(0) \delta(\omega)$
Convolution in time domain	$x(t) * v(t) \leftrightarrow X(\omega)V(\omega)$
Multiplication in time domain	$x(t)v(t) \leftrightarrow \frac{1}{2\pi} X(\omega) * V(\omega)$
Parseval's theorem	$\int_{-\infty}^{\infty} x(t)v(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} \overline{X(\omega)} V(\omega) d\omega$
Parseval's theorem (special case)	$\int_{-\infty}^{\infty} x^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X(\omega) ^2 d\omega$
Duality	$X(t) \leftrightarrow 2\pi x(-\omega)$

## Common Fourier Transform Pairs

$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$	$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$
1 $(-\infty < t < \infty)$	$2\pi \delta(\omega)$
$-0.5 + u(t)$	$\frac{1}{j\omega}$
$u(t)$	$\pi \delta(\omega) + \frac{1}{j\omega}$
$\delta(t)$	1
$\delta(t - c)$	$e^{-j\omega c} \quad (c \text{ any real number})$
$e^{-bt} u(t)$	$\frac{1}{j\omega + b} \quad (b > 0)$
$e^{j\omega_0 t}$	$2\pi \delta(\omega - \omega_0) \quad (\omega_0 \text{ any real number})$
$p_\tau(t)$	$\tau \text{sinc} \frac{\tau\omega}{2\pi}$
$\tau \text{sinc} \frac{\tau t}{2\pi}$	$2\pi p_\tau(\omega)$
$\left(1 - \frac{2 t }{\tau}\right) p_\tau(t)$	$\frac{\tau}{2} \text{sinc}^2 \left(\frac{\tau\omega}{4\pi}\right)$
$\frac{\tau}{2} \text{sinc}^2 \frac{\tau t}{4\pi}$	$2\pi \left(1 - \frac{2 \omega }{\tau}\right) p_\tau(\omega)$
$\cos(\omega_0 t + \theta)$	$\pi [e^{-j\theta} \delta(\omega + \omega_0) + e^{j\theta} \delta(\omega - \omega_0)]$
$\sin(\omega_0 t + \theta)$	$j\pi [e^{-j\theta} \delta(\omega + \omega_0) - e^{j\theta} \delta(\omega - \omega_0)]$

## Trigonometric identities

$$\sin(-\theta) = -\sin(\theta) \quad \cos(-\theta) = \cos(\theta) \quad \tan(-\theta) = -\tan(\theta)$$

$$\sin^2(\theta) + \cos^2(\theta) = 1 \quad \sin(2\theta) = 2 \sin(\theta) \cos(\theta)$$

$$\cos(2\theta) = \cos^2(\theta) - \sin^2(\theta) = 2 \cos^2(\theta) - 1 = 1 - 2 \sin^2(\theta)$$

$$\sin(\theta_1 + \theta_2) = \sin(\theta_1) \cos(\theta_2) + \cos(\theta_1) \sin(\theta_2) \quad \cos(\theta_1 + \theta_2) = \cos(\theta_1) \cos(\theta_2) - \sin(\theta_1) \sin(\theta_2)$$

$$e^{j\theta} = \cos(\theta) + j \sin(\theta)$$